### A Framework for Segmentation of Interview Videos

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#### **Abstract**

In this paper, we present a method to remove commercials from interview videos, and to segment interviews into host or interviewee shots. In our approach, we mainly rely on information contained in shot transitions, rather than analyzing the scene content of individual frames. We utilize the inherent differences in scene structure of commercials and interviews to differentiate between them. Similarly, we make use of the well-defined structure of interviews, which can be exploited to classify shots as questions or answers. The entire show is first segmented into camera shots based on color histogram. Then, we construct a data-structure (shot connectivity graph) which links similar shots over time. Analysis of the shot connectivity graph helps us to automatically separate commercials from program segments. This is done by first detecting stories, and then assigning a weight to each story based on its likelihood of being a commercial. Further analysis on stories is done to distinguish shots of the interviewer from shots of the interviewees. We have tested our approach on several full-length Larry King shows (including commercials) and have achieved video segmentation with high accuracy. The whole scheme is fast and works even on low quality video (160x120 pixel images at 5 Hz).

**Keywords**: Video segmentation, video processing, digital library, story analysis, semantic structure of video, removing commercials from broadcast video, Larry King Live show

### 1. Introduction

We live in the digital age. Pretty soon everything from TV shows to movies, documents, maps, books, music, newspapers, etc will be in the digital form. Storing videos in digital format removes the limitations of sequential access of video (for example forward and rewind buttons on a VCR). Videos may be more efficiently organized for browsing and retrieval by exploiting their semantic structure. Such structure consists of *shots* and groups of shots called stories. A story is one coherent section of a program or commercials. The ability to segment a video into

stories gives the user the ability to browse using story structure, rather than just sequential access available in analog format tapes.

In this paper, we consider one popular TV show, Larry King Live, which has been running for more than 15 years on CNN. We assume the entire collection of shows has been digitized, and address the problem of how to organize each show, so that it is suitable for browsing and retrieval. We consider the user may be interested to look at only interview segments without the commercials, or may want to view only clips which record the questions asked during the show, or may want to see only clips which record the answers of the interviewee. For example, the user might be motivated only to watch the questions, to get a summary of the topics discussed in a particular program.

Interview videos are an important segment of news-broadcast networks. Interviews occur within regular news and as separate programs. A lot of popular prime-time programs are based heavily on the interview format, for example, Crossfire, talk shows etc. The algorithm presented in this paper, though tested only for Larry King Live show, is not specific for any program and can be applied to these other shows to study their structure. This should significantly improve the digital-organization of these shows for browsing and retrieval purposes.

There has been lots of interest recently in video segmentation and automatic generation of digital libraries. The Informedia Project [1] at Carnegie Mellon University has spearheaded the effort to segment and automatically generate a database of news broadcasts every night. The overall system relies on multiple cues, like video, speech, closecaptioned text and other cues. Alternately, some approaches rely solely on video cues for segmentation [2, 3, 4]. Such an approach reduces the complexity of the complete algorithm and does not depend on the availability of close-captioned text for good results.

In this paper, we exploit the semantic structure of the show to not only separate the commercials from interview segments, but also to analyze the content of the show to detect host shots versus guest shots. All this is done using only video information and relying mainly on the information contained in shot transitions. No specific training is done for this particular show, and therefore, the scheme should be generalizable to other similar shows and programs.

In related work, in [5] the authors present a heuristic approach to segment commercials and individual news stories. They rely heavily on the fact that commercials have more rapidly changing shots than programs and are separated by blank frames. The overall error reported is high. Our approach to separate commercials and non-program segments exploits scene structure rather than multiple heuristics based on shot change rate. We are able to achieve high accuracy in our results.

In another work in [2], a scene transition graph is used to extract scene structure of sitcoms. We employ a similar data-structure in our computations. However, our work differs from their work in some important respects. In [2] all *cut edges* are treated as story boundaries. This paradigm would result in a high number of stories for non-repetitive scenes, like commercials. Their approach, therefore, would not work well in separating commercials from programs. In addition, we employ a novel weighing scheme (see Section 3) for each story to distinguish commercials from programs. We also analyze the story for its content, rather than simply finding its bounds.

In the next section, we discuss the algorithm to detect shot boundaries and build the shot connectivity graph. In Section 3, we present our scheme to detect interview segments and separate them from commercials. In Section 4, we analyze the interview stories found by our algorithm to label host shots and guest shots. Finally we present the results in Section 5.

### 2. Shot Connectivity Graph

The first step in processing the input video is to group the frames into *shots*. A shot is defined as a continuous sequence captured by a single camera. We use a modified form of the algorithm described in [7] for the detection of shot boundaries, allocating 8-bins for hue and 4-bins each for saturation and intensity values. Let the normalized histogram be denoted by  $H_i$ , where i is the frame-number. Let D(i) represent the histogram intersection of frames i and the previous frame i-1. That is

$$D(i) = \sum_{j \in \text{ all bins}} \min(H_i(j), H_{i-1}(j))$$
 (1)

Then we define the shot change S(i) measure as

$$S(i) = D(i) - D(i-1)$$
 (2)

In [7], a threshold was applied to D(i) to find shot boundaries. We, however, found out that a threshold applied to S(i) does a better job in finding shot boundaries. Note that D(i) is bound between [0,1], and S(i) is the derivative of D(i).

For each shot that we extract, we find a key frame representing the content of that shot. The key frame is defined as the middle frame between the two shot boundaries. Once shot boundaries have been identified, they are organized into a data-structure, which we call *shot connectivity graph G*. This graph links similar shots over time, thus extracting the semantic structure of video and making the segmentation task easier. The vertices *V* represent the shots. Each vertex is assigned a label indicating the serial number of shot in time and a weight *w* which is the number of frames in that particular shot.

The process of inserting edges to connect the vertices in the shot connectivity graph consists of finding the intersection of the histogram of each key frame with those of previous key frames to determine whether a similar shot had occurred before or not. However, this process is time-constrained to only a certain number of previous shots (the memory parameter,  $T_{mem}$ ). Thus, shot proximity i.e. shots that are close together in time, and shot similarity i.e. shots that have similar color statistics, are two criteria to link the vertices in the shot connectivity graph. For shot q to be linked to shot q-k (where  $k \leq T_{mem}$ ) the following condition must hold true:

$$\sum_{j \in \text{ all bins}} \min(H_q(j), H_{q-k}(j)) \geq T_{color}$$
 for some  $k \leq T_{mem}$  (3)

where  $T_{color}$  is a threshold on the intersection of histograms and captures the allowed tolerance between color statistics of two shots for them to be declared similar.

It is important to point out here that we have not employed a time constraint on the number of frames, as in some previous approaches. Rather, we have used a constraint on the number of shots, which makes our scheme more robust. Commercials generally have rapidly changing shots and therefore this threshold would translate into a shorter time constraint, whereas interviews would span more frames within the same number of shots. This results in a larger time constraint for interviews, which yields more meaningful segmentation.

Significant story boundaries (for example that between the show and the commercials) are often separated by a short blank sequence. This is done to provide a visual cue to the audience that the following section is a new story. These blanks can be found by putting a test on the histogram  $H_i$  to check if all the energy in the histogram is concentrated into a single bin.

We utilize these blanks to avoid making links across a blank in our shot connectivity graph. Thus two vertices  $\nu_p$  and  $\nu_q$ , such that  $\nu_p, \nu_q \in V$  and p < q, are adjacent ,that is they have an edge between them , if and only if

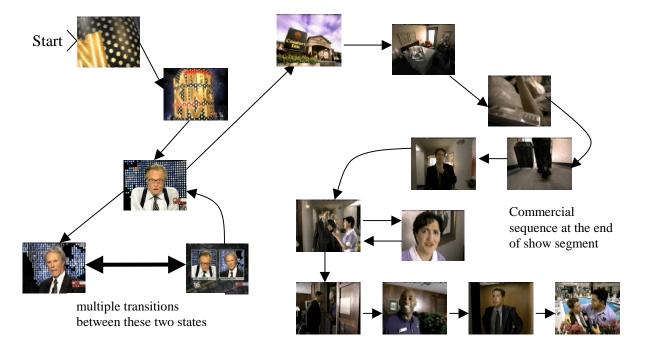


Figure 1: Shot Connectivity Graph: Note the high repetitive structure of the interview segment, versus the linear structure of the commercial sequence. Even though commercials also have loops (as shown), our algorithm is able to separate them from the interview segment.

- $v_p$  and  $v_q$  represent consecutive shots or
- v<sub>p</sub> and v<sub>q</sub> satisfy the shot similarity, shot proximity and blank constraints.

The shot connectivity graph exploits the structure of the video selected by the producers in the editing room. Interview videos are produced using multiple cameras running simultaneously in time, recording the host and the guest. The producers switch back and forth between them to fit these parallel events on a sequential tape. By extracting this structure, different story segments can be differentiated from each other. Not only that, but we can achieve understanding of the story *content* by looking closely at the structure. This follows from the fact that scene structure is not arbitrary, but is carefully selected by the producers for best user perception. An example of the shot connectivity graph for a section of Larry King Live show is shown in Figure 1.

## 3. Story Segmentation and Removal of Commercials

Interviews have a very strong semantic structure that relates them in time. Typical scenes of interview shows have alternating shots of the host and the guests, including shots of single or multiple guests in the studio, split shots of guests in the studio with guests at another location, and shots of both the host and the guests. These shots are strongly intertwined back and forth in time, and prove to be the key cue in discriminating them from other stories.

Commercials on the other hand have weak structure and rapidly changing shots (see Figure 1). There might still be repetitive shots in a commercial sequence, which appear as cycles in the shot connectivity graph. However, these shots are not as frequent, or as long in time, as those in the interview. Moreover, since our threshold of linking shots back in time is based on the *number of shots*, and not on the total time elapsed, commercial segments will have less time memory than interviews.

We contend here that simply relying on the hypothesis that commercials have more rapidly changing shots than programs for segmenting commercials [5] is not enough. Even good stories might occasionally have a high rate of change of shots, due to either video summaries shown within the program or just multiple people trying to speak simultaneously within the interview. Exploiting scene structure, however, is more robust and takes care of these situations.

Our scheme to differentiate commercial sequences from program sequences relies on analysis of the shot connectivity graph. Commercials generally appear as a string of states, or small cycles in the graph. To detect them, we find *stories*, which are collection of shots linked, backed in time. To extract stories from the shot connectivity graph G, we find all the strongly connected components in G. A strongly connected component G'(V', E') of G has the following properties

- $G' \subseteq G$
- There is a path from any vertex  $v_p \in G'$  to any other vertex  $v_q \in G'$ .
- There is no  $V_z \in (G G')$  such that adding  $V_z$  to G' will form a strongly connected component.

Each strongly connected component G' in Grepresents a story. We compute the likelihood of all such stories being part of an interview segment or not. Each story is assigned a weight based on two factors; the number of frames in a story and the ratio of number of repetitive shots to the total number of shots in a story. The first factor follows from the observation that long stories are more likely to be interview segments than commercials. Stories are determined from strongly connected components in the shot connectivity graph. Therefore, a long story means that we have observed multiple overlapping cycles within the story since the length of each cycle is limited by  $T_{mem}$ . This indicates the strong semantic structure of the program. The second factor stems from the observation that interview programs have a large number of repetitive shots in proportion to the total number of shots. Commercials, on the other hand, have a high shot transition rate. Even though commercials may have repetitive shots, this repetition is small compared to total number of shots. Thus program segments will have more repetition than commercials, relative to total number of shots. Both of these factors are combined in the following likelihood of a story being an interview segment:-

$$L(G') = \sum_{\forall j \in G'} w_j \frac{\sum_{j \in G' \mid j > i}}{\sum_{\forall j \in G'} 1} \Delta t$$
 (5)

where G' is the strongly connected component representing the story.  $w_j$  is weight of the jth vertex i.e. the number of frames in shot j. E' are the edges in G'.  $\Delta t$  is the time interval between consecutive frames. Note that the denominator represent the total number of shots in the story.

This likelihood forms a weight for each story, which is used to decide on the label for the story. Stories with L(story) higher than a certain threshold are labeled as interview stories, whereas those that fall below the threshold are labeled as commercials. This scheme is robust and yields accurate results, as shown in Section 5.

# 4. Host Detection: Analysis of Shots within an Interview Story

We perform further analysis of interview stories, extracted by the method described in the pervious section, to differentiate host shots from guest shots. Since the host is asking questions, which are typically shorter than the answers, this observation can be



Figure 2: Examples of host detection:
(a) Correct host detection (Leeza Gibbons substituting for Larry King in one show). Correct classification is achieved even for varying poses. (b) Guest shots; Larry King shot is misclassified due to occlusion of the face.

utilized for successful segmentation. Even though our domain is limited to one particular show, we have not used any specific training to detect Larry King as the host. Instead, the host is detected from the pattern of shot transitions, exploiting the semantics of scene structure. This statement is verified by the fact that one of our test videos had another person substituting for Larry King and worked with equal accuracy.

For a given show, we first find *N* shortest shots in the show containing only one person, where *N* was fixed at 8 in our experiments. To determine if a shot has one person or more, we use the skin detection algorithm presented in [6]. A skin color predicate is first trained on a few training images, by manually marking skin regions and building a 3D-color histogram of these frames. For each positive example, the histogram is incremented by a 3D Gaussian distribution, so that colors similar to the marked skin color also get selected. For each negative training example, the histogram is decremented by a narrower Gaussian. After incorporating information from all training images, the color predicate is thresholded to a small positive value, and thus essentially forms a

Results	Total	Interview Segments	Interview Segments	Misclassified Frames	Misclassified Frames	Total Error	Overall Correct Classification
	Frames	Ground truth	found	(False +ve)	(False –ve)	%	%
Video 1	34611	8	8	12	36	0.14	99.86
Video 2	12144	6	6	4	17	0.17	99.83
Video 3	17157	8	9	287	108	2.30	97.70
Video 4	13778	6	6	105	2	0.78	99.22

Table 1: Detection of interview segments. Video 1 was digitized at twice the frame-rate (10 Hz) of the rest of the videos

Results	Total	Interview Segments	Interview Segments	Classification Error	Classification Error	TotalError	OverAll Correct
	Frames	ground truth	found	(False +ve)	(False -ve)	%	Classification, %
Video 1	34611	8	8	12	890	2.61	97.39
Video 2	12144	6	6	4	17	0.17	99.83
Video 3	17157	8	9	6	1804	10.55	89.45
Video 4	13778	6	6	105	265	2.69	97.31

Table 2: Detection of interview segments, while considering outdoor videos as part of interviews. Note that the performance is lower than in Table 1, where outdoor videos were not considered part of the interview.

color lookup table. Including persons of various ethnic backgrounds in training images makes this color predicate robust for a variety of skin tones. For detection, the color of each pixel is looked up in the color predicate to be labeled as skin or non-skin. If the image contains only one significant skin colored component, then it is assumed to have one person in it.

The key frames of the *N* shortest shots containing only one person are correlated in time to find the most repetitive shot. Since questions are typically much shorter than answers, host shots are typically shorter than guest shots. Thus it is highly likely that most of the *N* shots selected will be host shots. An *N*-by-*N* correlation matrix **C** is computed such that each term of **C** is given by:

$$C_{ij} = \frac{\sum_{r \in \text{ allrows}} \sum_{c \in \text{ allcols}} (I_i(r,c) - \mu_i) (I_j(r,c) - \mu_j)}{\sqrt{\left(\sum_{r \in \text{ allrowd}} \sum_{c \in \text{ allcols}} (I_i(r,c))^2\right) \left(\sum_{r \in \text{ allrows}} \sum_{c \in \text{ allcols}} (I_j(r,c))^2\right)}}$$
(6)

where  $I_k$  is the gray-level intensity image of frame k and  $\mu_k$  is its mean. Notice that all the diagonal terms in this matrix are 1 (and therefore do not need to be actually computed). Also,  $\mathbf{C}$  is symmetric, and therefore only half of non-diagonal elements need to be computed.

The frame returns the highest sum for a row is selected as the key frame representing the host. That is,

$$HostID = \arg\max_{r} \sum_{c \in \text{allcols}} C_{rc} \quad \forall r$$
 (7)

Name	Correct	Host Detection	
	HostID?	Accuracy	
Video 1	Yes	99.32%	
Video 2	Yes	94.87%	
Video 3	Yes	96.20%	
Video 4	Yes	96.85%	

Table 3: Accuracy of Host Detection: Column 2 defines whether the correct host was found in the story or not. Column 3 gives the overall error in labeling host shots.

Figure 2 shows key host frames extracted for our test videos. Note that the correct host is identified in video 3 because she was substituting for Larry King. We identified the correct host for all our test videos using this scheme.

The key host frame is then correlated against key frames of all shots to find all shots of the host. For this algorithm, the same correlation equation (Eq. 6) is used. Results of this algorithm are compared against ground-truth marked by a human observer, and show high accuracy of this method (see Section 5 and Table 3).

#### 5. Results

Our test suite was 4 full-length Larry-King Live shows digitized at 160x120 size at 5 Hz. This is fairly low spatial and temporal resolution, but is sufficient to capture the kind of scene structure that we exploit. For each data-set, we digitized a short segment before and after the show, so that the start and the end of the actual interview is also captured within our data set. This program is broadcast in the evening during

prime time on CNN and contains significant commercial segments. One of the shows had a substitute person for Larry King. The shows had guests varying from one to three. The thresholds in algorithms were kept the same, and the same skin color predicate was used for all data-sets.

Sometimes, in interview programs, short movie videos are shown which are relevant to the topic being discussed. Table 1 presents results not considering such videos as a part of the interview. If our aim is to eventually label host versus guest shots then this is a valid assumption. However, if the aim is extract the full show as a segment, then not including these videos will be a misclassification. Table 2 presents results for the same videos but here these ending movie sequences are considered part of the interview. This gives us a slightly higher rate of false negatives. However, the overall performance is still high and we are able to extract the commercials accurately, as is evident by the results.

Table 3 contains host detection results with the ground truth established by a human observer. The second column shows whether the host identity was correctly established or not by Eq. 7. The last column shows the overall rate of misclassification of host shots. Note that for all four videos, very high accuracy and precision is achieved by our algorithm.

### 6. Conclusions

We have used the information contained in shot transitions to differentiate between commercials and interview segments for several Larry King Live shows. We have also segmented stories into host shots and guest shots. This creates a better organization of these shows than simple sequential access. The user may browse just the questions to extract a meaningful summary of the whole show in a small amount of time.

We have demonstrated that shot transitions of video alone are sufficient to perform these tasks to a high degree of accuracy, without using speech or close-captioned text. We also perform minimal image content analysis. The entire scheme is efficient and works on low spatial and temporal resolution video.

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